

Torque on Current Loop

→ Consider rectangular current loop

- ◆ Forces in left, right branches = 0
- ◆ Forces in top/bottom branches cancel
- ◆ No net force! (true for any shape)

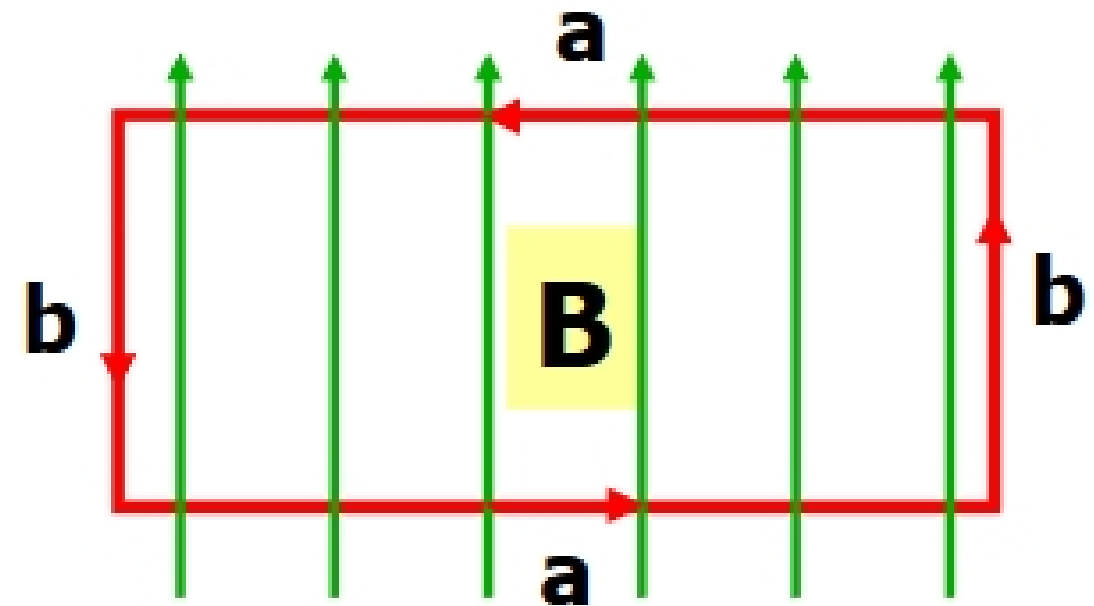
→ But there is a net torque!

- ◆ Bottom side up, top side down (RHR)
- ◆ Rotates around horizontal axis

$$\tau = Fd = (iBa)b = iBab = iBA$$

→ $\mu = NiA \Rightarrow$ "magnetic moment" (N turns)

- ◆ True for any shape!!
- ◆ Direction of μ given by RHR

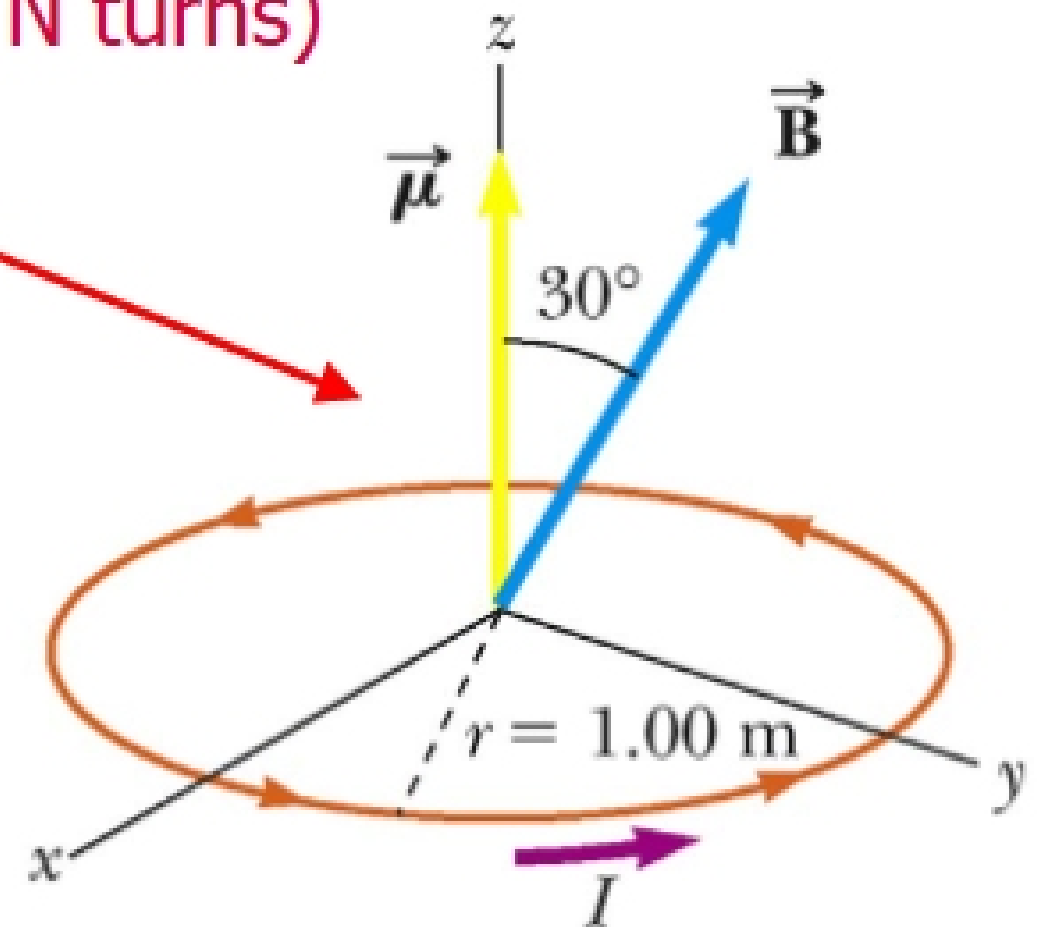


Plane normal is $\perp B$ here

General Treatment of Magnetic Moment, Torque

→ $\mu = NiA$ is magnetic moment (with N turns)

◆ Direction of μ given by RHR

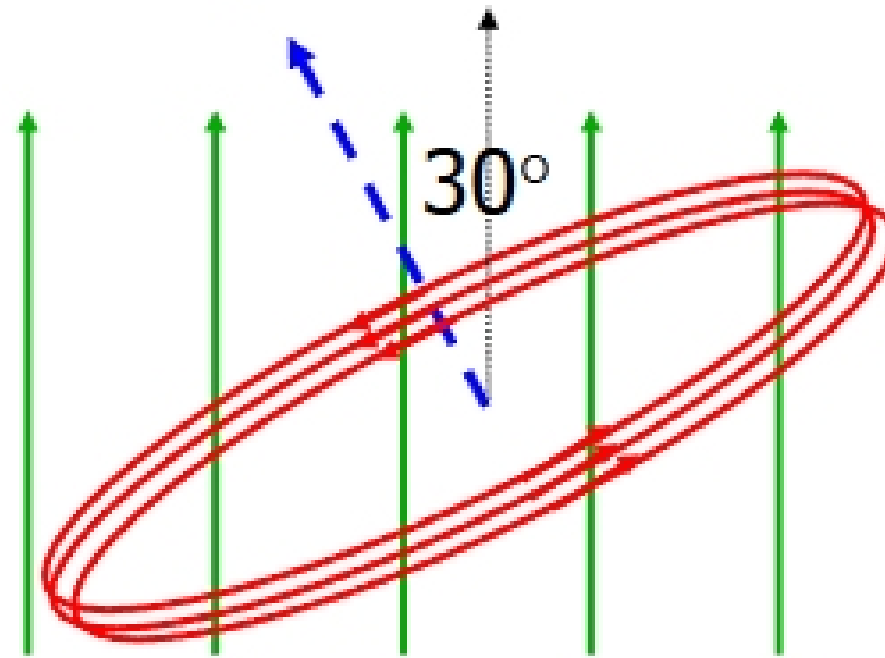


→ Torque depends on angle θ between μ and B

$$\tau = \mu B \sin \theta$$

Torque Example

- A 3-turn circular loop of radius 3 cm carries 5A current in a B field of 2.5 T. Loop is tilted 30° to B field.



→ $\mu = 3i\pi r^2 = 3 \times 5 \times 3.14 \times (0.03)^2 = 0.0339 \text{ A} \cdot \text{m}^2$

→ $\tau = \mu B \sin 30 = 0.0339 \times 2.5 \times 0.5 = 0.042 \text{ N} \cdot \text{m}$

- Rotation *always* in direction to align μ with B field