

# Tortion Mirror Switch

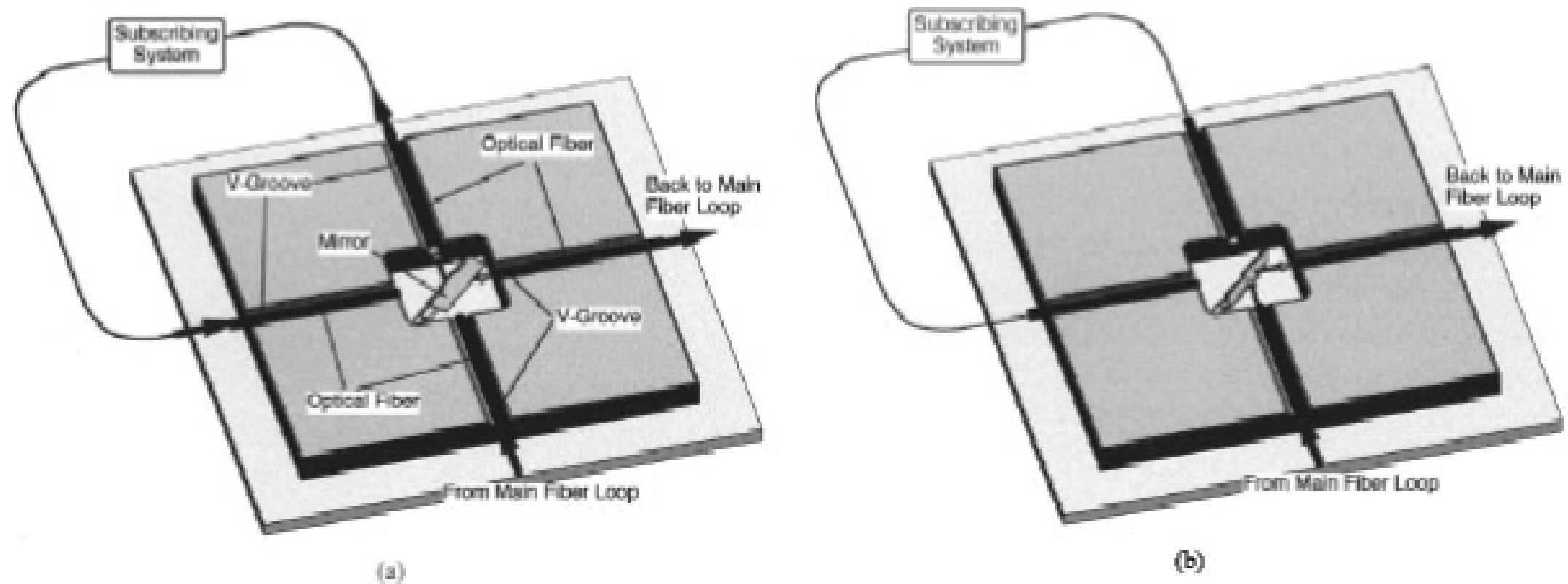


Fig. 1. Schematic view of micromechanical fiber-optic crossconnector of a torsion mirror. (a) Mirror at the rest position. (b) At active position.

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# Tortion Mirror Equations

The magnetic torque  $T_m$  produced by an applied magnetic field  $H_d$  is:

$$T_m = V_m M_s H_d \sin(\pi/2 - \theta)$$

where  $M_s$  is the saturation magnetization and  $V_m$  is the volume of magnetic material on the mirror.

The mechanical restoring torque of the torsion beam is:

$$T_r = [2(Gwt^3\theta)/3l] \{ (1 - 192/\pi^5)(t/w)[\tanh(\pi w/2t)] \}$$

where  $l$ ,  $w$  &  $t$  are the length, width & thickness of the beam and  $G$  is the shear modulus of silicon.

Setting these two equations equal to each other gives the values of  $\theta$  as a function of magnetic field

# Rotary Electrostatic Micromotor

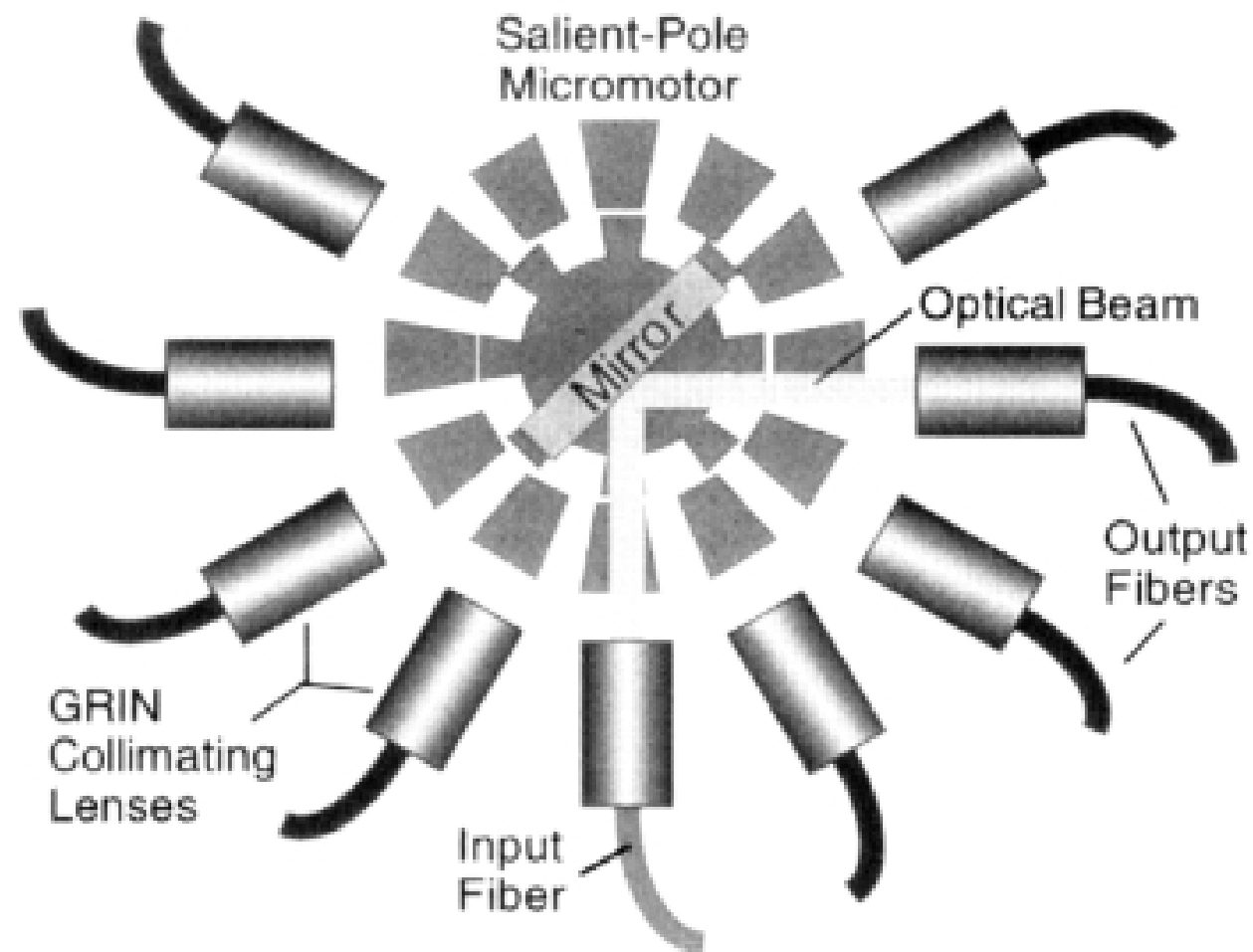


Fig. 1. Rotary-mirror optical test setup showing the eight possible output channels and an example switch position to the 90° output channel.

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