

## Study recommendations.

Work the 19 final exam review problems. Solutions will be posted in groups. The solutions for the first 5 problems (chapters 1, 2, 3) will be posted on Tuesday (tomorrow).

Look at mid-term review problems.  
Go over the homework problems.

Leaf through the chapters and make sure you understand the boxed equations.

Read the text and study the examples.

In class today, I showed some slides pertaining to chapters 1, 2, 3 that were used previously. What follows here are just the overviews of those three chapters.

# Chapter 1 Retrospective

## Vectors

Dot product  $\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta$

Orthonormal bases  $\vec{e}_i$

Components  $A_i = \vec{A} \cdot \vec{e}_i$

Cross product  $\vec{A} \times \vec{B}$  length  $|\vec{A}| |\vec{B}| \sin \theta$

Derivative operator  $\vec{\nabla}$  "del"

Gradient  $\vec{\nabla} f$

Divergence  $\vec{\nabla} \cdot \vec{A}$

Curl  $\vec{\nabla} \times \vec{F}$

Laplacian  $\nabla^2 f = \vec{\nabla} \cdot \vec{\nabla} f$

Polar coordinates (spherical, cylindrical)

Gauss' Law

$$\int_V \vec{\nabla} \cdot \vec{g} \, dv = \int_A \vec{g} \cdot d\vec{a}$$

$A =$  oriented boundary of  $V$

Stokes' Theorem

$$\int_A (\vec{\nabla} \times \vec{F}) \cdot d\vec{a} = \int_C \vec{F} \cdot d\vec{l}$$

$C =$  oriented boundary of  $A$

## Chapter 2 Review

$$\vec{F} = m\vec{a}$$

Solve for  $\vec{r}(t)$ , position as function of time, given a starting position  $\vec{r}(0)$  and initial velocity  $\vec{v}(0)$ , using a known force  $\vec{F}(\vec{r})$ .

### Examples

Sliding on an inclined plane

Projectile motion

Weight with ropes and pulleys.


Conservative force:  $\vec{F} = -\vec{\nabla}U \Leftrightarrow \vec{\nabla} \times \vec{F} = 0$

Examples: gravity  $\vec{F} = -mg\vec{k}$   $U = mgz$   
Spring  $\vec{F} = -k(x-x_0)$   $U = \frac{1}{2}k(x-x_0)^2$

Non-conservative force  $\vec{\nabla} \times \vec{F} \neq 0$ , no potential energy.

Examples: Friction

Air resistance

Work  $W = \int_1^2 \vec{F} \cdot d\vec{r}$  

Path independence  $\Leftrightarrow$  "work function"  $\Leftrightarrow$  potential energy

$T + U = \text{constant}$  if motion is governed by a conservative force with potential energy  $U$ .

$T = \text{kinetic energy} = \frac{1}{2}mv^2$