

PRIMER ON ERRORS

8.13 U. Becker 9,2006

- v Random & Systematic Errors
- v Distribution of random errors
- v Binomial, Poisson, Gaussian
- v Poisson \leftrightarrow Gaussian relation
- v Propagation of Errors
- v Fits

Reading assignment: Bevington CH.1-3

No measurement has infinite accuracy or precision"

K.F. Gauss: "In experimental physics a numbers must have an error and a dimension."

$$G = (6.67310 \pm 0.00010) [\text{m}^3 \text{kg}^{-1} \text{s}^{-2}]$$

Errors = deviations from Truth (unknown, but approached)

Large error: Result is not significant & controversial.

Small error: Good measurement, will test present/future theories.

Blunders are blunders never errors – repeat on Fridays correctly.

Two types:

Random Errors - repeated measurements give (slightly) different results

Systematic Errors "in the system" DVM 2% low... correct if you can, otherwise quote separate

Systematic error: inherent to the system or environment

example:

Measure g with a pendulum: $T = 2\pi\sqrt{\frac{l}{g}}$

- neglect m of thread)
- equipment (accuracy of scale, watch)
- environment (wind, big mass in basement)
- thermal expansion
 1. correct by $l = l_0(1 + \alpha t)$ if t known or
 2. give sys.error Δ_t from est. range of t.

⇒ **limits ACCURACY** (=closeness to truth)

