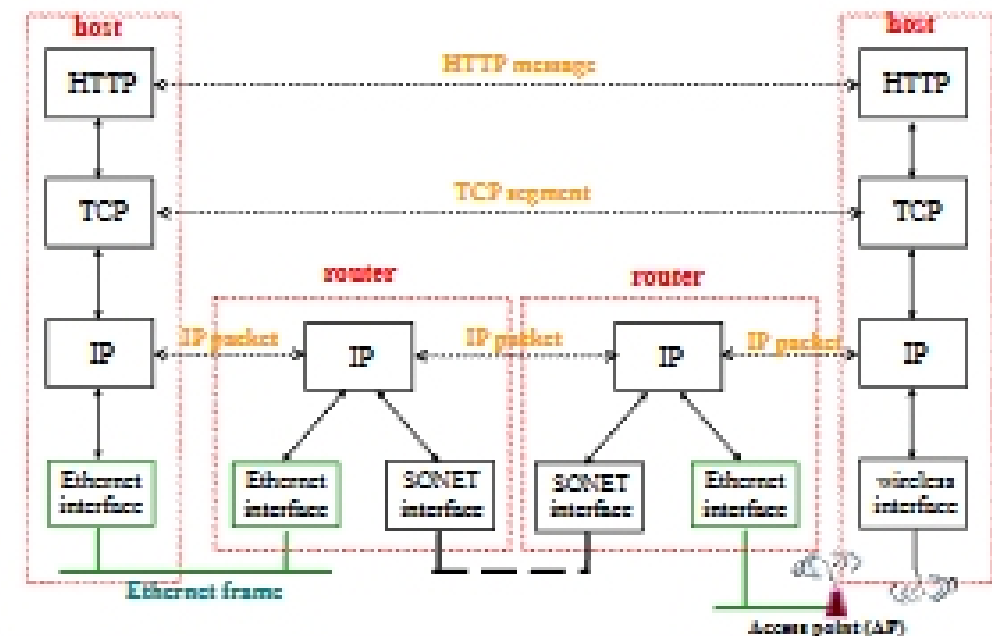


## About the Final Exam

- ♦ Saturday June 4 3:00-6:00PM
- ♦ Open book, open notes; no computers
- ♦ Material to be covered
  - Chapter 2: focusing on 2.2 & 2.5
  - Chapter 3: focusing on TCP (3.5 & 3.7)
  - Chapter 4: 4.4 ~ 4.7
  - Chapter 5: 5.3 ~ 5.6
  - Chapter 6: 6.3 and 6.5
- ♦ The objective: testing the overall understanding of the material

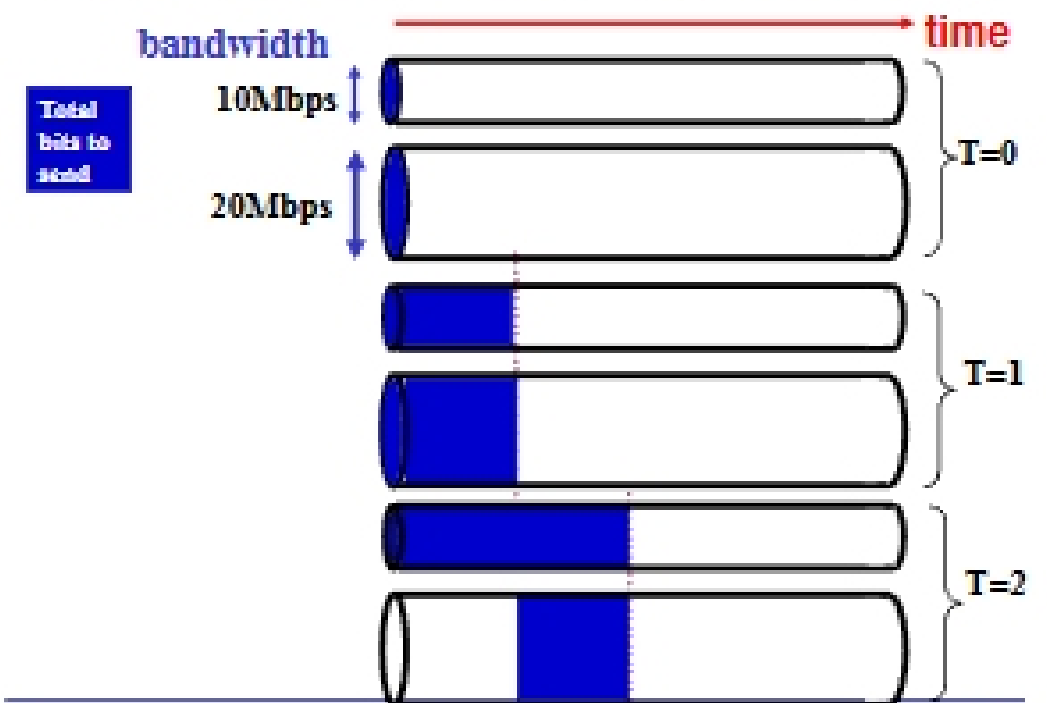
## The big picture



## A Bottom-up Roadmap

- ♦ Physical layer: know how to calculate the delay of sending packets from one node to another
  - Transmission rate (bandwidth)
  - Transmission delay
  - Propagation delay
- ♦ Link layer: move data between two directly connected nodes
  - Error checking schemes: parity, checksum, CRC
  - Framing, byte stuffing
  - Multi-access protocols: Aloha, Ethernet (CSMA/CD), 802.11 (CSMA/CA)
  - MAC address, Address Resolution Protocol
  - Switch/bridge self-learning scheme

## Bandwidth, transmission delay, propagation delay



## Above link layer

- ◆ Network layer
    - IP header, IP address structure (subnet, CIDR)
    - Routing: distance vector, link state; BGP; broadcast, multicast, IGMP
  - ◆ Transport layer
    - UDP, TCP: header format
    - TCP
      - connection set-up & tear-down
      - congestion control
      - retransmission timer setting
    - Mechanisms for reliable data delivery; relations among sequence number, window size, RTT
  - ◆ Application layer protocols
- 

CS-14

## Packet switching

- ◆ Why packet switching?
  - ◆ Packet: data chopped into chunks
  - ◆ Forwarded in a "store-and-forward" way
    - Statistical multiplexing → queueing delay, potential losses
  - ◆ Delays in the network
    - Transmission delay: packet-size/bandwidth
    - Propagation delay: link-length/prop. Delay
    - Store-and-forward delay
    - Queueing delay
- 

CS-14

## Data link layer

- ◆ You need to know the concepts of (1)framing; (2)byte stuffing; (3)bit error detection
  - ◆ Link layer address: MAC addresses (Medium Access Control)
    - not IP address!
    - flat address space
    - Need ARP to map IP to MAC address
  - ◆ Channel access protocols for multiaccess channels (e.g. Ethernet, wireless LAN)
- 

CS-14

## Random multi-access protocol

- ◆ Multi-access: *single* communication channel *shared* by multiple nodes, only one node can send *successfully* at a time
  - ◆ Aloha/Slotted Aloha
    - Q: for a network with 3 nodes, what is the probability that a given node sends a data frame successfully without collision?
  - ◆ Ethernet
    - 1-persistent CSMA/CD
      - Q: Why need collision detection?
    - Collision resolution: Q: how the exponential backup works
  - ◆ 802.11 wireless LAN
    - CSMA/CA
      - Q: why doing collision avoidance instead of collision detection?
    - RTS-CTS
- 

CS-14

## Aloha example

- $P(\text{success by a given node}) = p \cdot (1-p)^{(N-1)}$
- $N=3$ , if  $P = 0.2$ ,  $p \cdot (1-p)^{(N-1)} = 0.2(0.8)^2 = 0.08$
- $P(\text{success by any node}) = N p \cdot (1-p)^{(N-1)}$
- As  $N \rightarrow \text{large}$ ,  $P_{\text{max}}(\text{success by any node}) = 1/2e$
- Maximum throughput?  $1\text{Mbps} \cdot 0.18 = 180\text{Kbps}$

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CS-18

## Ethernet: collision detection and recovery

A: sense channel, wait if necessary until it is idle  
 transmit and monitor the channel;  
 If detect another transmission  
 then {  
   abort and **send jam signal**;  
   update # collisions ( $n++$ );  
   delay for  $K \times 512\text{bits transmission time}$   
   goto A.  
 }  
 else {done with the frame; set #collisions to zero ( $n = 0$ )}

**Jam Signal:** make sure all other transmitters aware of the collision

Exponential Backoff algorithm:

- first collision ( $n=1$ ): choose  $K$  from  $\{0, 1\}$  (i.e.  $\{0, 2^n - 1\}$ )
- after second collision ( $n=2$ ): choose  $K$  from  $\{0, 1, 2, 3\}$ ...
- after 10 collisions ( $n=10$ ), choose  $K$  from  $\{0, 1, 2, 3, 4, \dots, 1023\}$

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## Ethernet: CSMA/CD

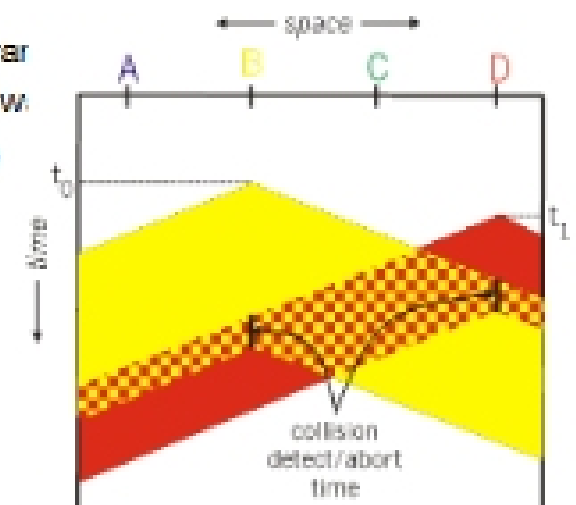
- Carrier Sense Multiple Access with Collision detection

Listen before transmit

- If channel sensed idle: transmit
  - If channel sensed busy, wait
- But collisions still possible

- To cut the loss early:  
**Collision Detection:**  
 compare transmitted with received signals

- Abort collided transmissions

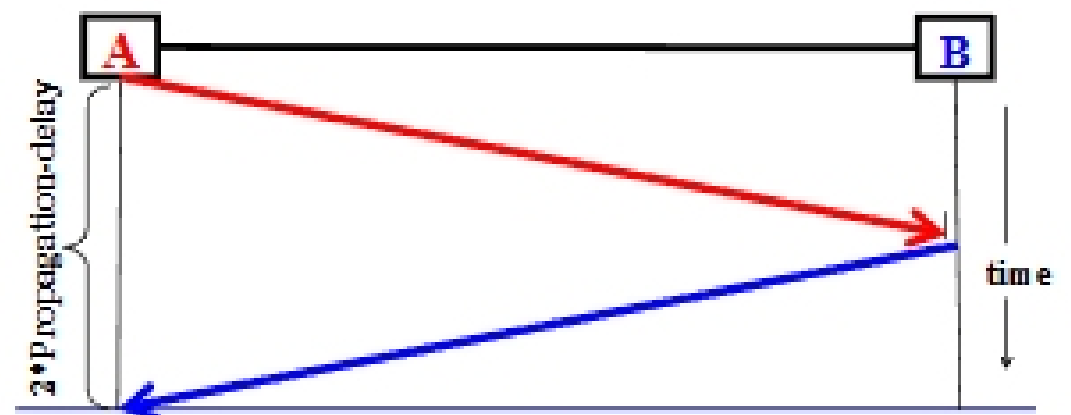


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## Why Ethernet has a lower bound on frame size?

- Ethernet transceiver can send & listen at same time
  - If the received data stream differs from the one transmitted  
 → collision
- to detect a collision: the sender must still be transmitting when garbled signal propagates back



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