Image Precision Silhouette Edges

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Abstract

Finding and displaying silhouette edges is important in applications ranging from computer vision to nonphotorealistic rendering. To render visible silhouette edges of a polygonal object in a scene from a given viewpoint, we must first find all silhouette edges, i.e. boundaries between adjacent front facing and back-facing surfaces. This is followed by solving the partial visibility problem so that only those parts of silhouette edges, which are not occluded by interior of any front facing surface, are rendered. The scene may optionally be rendered with a lighting model. This paper describes a simple general-purpose method to combine all three operations for any scene composed of objects that can be scan-converted. Using a depth buffer, the rendering process computes the intersection of adjacent front facing and back-facing surfaces in image space at interactive rates. All operations are performed in image-precision and hence special care is taken for the limited numerical precision of the depth buffer. A solution is suggested using view-dependent modification of polygonal objects. The method does not require any preprocessing or adjacency information and hence is applicable for dynamic scenes.

1. INTRODUCTION

Traditional computer graphics, specifically real-time graphics, usually goes to great lengths to be as photorealistic as possible. However, a simplified diagram is often preferred when an image is required to delineate and explain. Silhouette edges are useful to effectively convey a great deal of information with a very few strokes using nonphotorealistic rendering (NPR). Except [Rossignac92][Markosian97] [Zeleznik96] though, NPR methods have primarily been batch oriented rather than interactive. Most of the techniques are object precision and rely on a-priori information about object models such as the connectivity between surfaces.

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Our method assumes that the scene is made up of oriented polygons. To render only visible silhouette edges from a given viewpoint, we must

(a) find all silhouette edges, i.e. boundaries between adjacent front facing and back-facing polygons, and
(b) solve the partial visibility problem to render only those parts of silhouette edges, which are not occluded by the interior of any front facing polygons.

The visible polygon interiors may optionally be rendered with a lighting model

Our method is based on the observation that only two sets of primitives are needed to compute silhouette edges, the first and second layer of polygons from a given viewpoint. In other words, these include the visible polygons and the layer just behind them which may be either front facing or back facing. Intersection of these two sets gives silhouette edges. In this paper we propose a method specifically for polygonal models but it can be extended to models in any representation for which these two layers or their intersection can be computed. In the proposed method the two nearest layers and their intersection are computed in real time in image precision. The method is robust, general purpose and easy to implement. No pre-processing or adjacency information is required. This allows use of silhouette edges in dynamic scenes, models with changing topology or in models with different levels of detail using traditional polygon rendering pipeline. We also describe how this method can be used to create interesting effects.

2. PREVIOUS WORK

Silhouette edges can be rendered using hidden line removal methods [Sutherland74], which are typically batch processes [Dooley90][Elber90]. The method proposed by Markosian et. al. [Markosian97] is real time and works on static polyhedral models with known adjacency information. They use a probabilistic method to identify silhouette edges. The visibility of silhouette edges is computed using modified Appel's hidden-line algorithm [Appel67] assuming the view is generic. The main advantage is that the whole scene does not need to be traversed and hence the silhouette edges of the model can be rendered at a higher frame rate than the model itself. The connectivity information is used to trace out entire silhouette curves by stepping along adjacent silhouette edges. Since the silhouette edges are identified individually, line segments between two vertices can be rendered in expressive styles, for example, in a wobbly, hand-drawn style. Zeleznik's SKETCH system [Zeleznik96] makes use of the polygon-rendering pipeline to highlight edges and boundaries. The method in [Rossignac92] is image precision and does not need adjacency information. The depth-buffer is first updated by rendering the scene in white. Next, after translating backwards, the scene is rendered in thick

wireframe mode in black. It does not address the issue of aliasing in the depth-buffer. The work described here is a generalization of the methods outlined in [Rossignac92].

3. METHOD

We describe an algorithm to render silhouette edges for polyhedral models in image space. An important observation is that only two sets of polygons are needed to compute visible silhouette edges for a given viewpoint. These two sets are ***P1***, the layer of visible polygons nearest the viewpoint, and ***P2***, the second layer of polygons from that viewpoint. Front facing as well as back-facing polygons are considered in determining these two sets. The intersection of ***PI*** and ***P2*** gives silhouette edges in object space. The first layer of visible polygons can be computed using any visibility algorithm. For a collection of polygonal models of closed objects, this layer is made up of front facing polygons that are completely visible (e.g. front-facing polygons of T_1 in Figure 1 .b) or visible sub-parts of front facing polygons that are partially visible (e.g. sub-parts of front-facing polygons of T_2 in Figure 1.b). The second layer can be computed using the same visibility algorithm as the first after subtracting the polygons in the first layer from the set of all polygons. This second layer, for closed objects, is made up of the back-facing polygons behind the visible surfaces (Figure 1 .c). If we assume the viewpoint is not inside any closed object and interiors of polygons do not intersect, the intersection of ***P1*** and ***P2*** gives the desired silhouettes (Figure 1 .d).

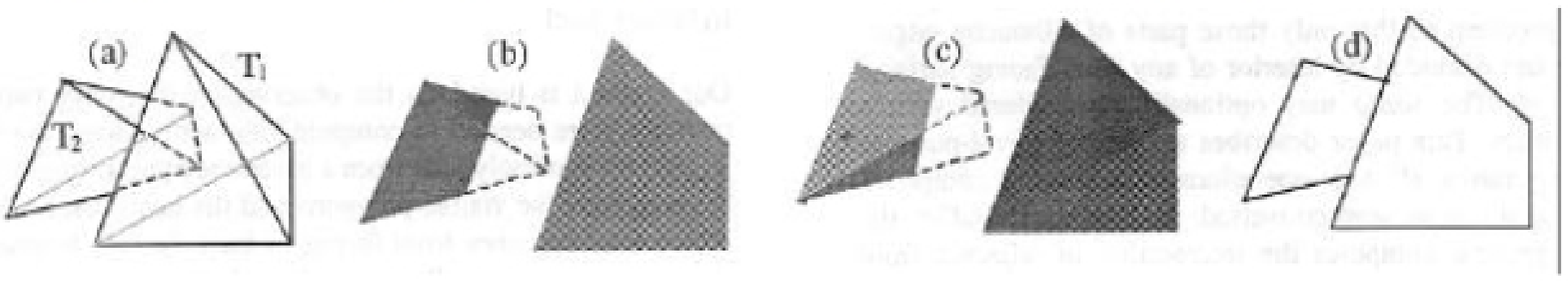

Figure 1. The first layer, ***PI***, for scene (a) is made up of parts of nearest front facing polygons (b), The second layer, ***P2***, is made up of parts of back facing polygons (c). The interesection of these two layers in image space creates silhouette edges (d).

We can render the silhouette edges by computing the projection of ***P1***, ***P2*** and ***P1*** $\cap$ ***P2*** using a depth buffer (i.e. Z-buffer) directly in image space. The locations where depth values due to ***PI*** and ***P2*** are equal correspond to the projection of the set ***P1*** $\cap$ ***P2***. The following is a pseudo-code to render silhouette edges in black on white background. (When the depth function is *f*, a pixel with depth d_1 overwrites the current pixel in the frame buffer with depth d_2, iff $f(d_1,d_2) = true$.)

Draw background with white color
Enable back face culling, set depth function to 'Less Than'
Render (front facing) polygons in white
Enable front face culling, set depth function 'Equal To'
Draw (back-facing) polygons in black
Repeat for a new viewpoint

This basic method, however, has many limitations. Due to pixel sampling and Z-buffer quantization it is possible that the depth values in the framebuffer due to ***P1*** and ***P2*** may never agree thus pixels closest to the silhouette may be missed. Further, the created silhouette edges will be at most one pixel wide.

3.1. Wireframe Rendering

The basic method can be slightly modified to render edges of back-facing polygons instead of filled back-facing polygons. Front facing polygons are rendered as before, but back-facing polygons are rendered in wireframe mode and the depth function is Less than or Equal'. In [Rossignac92], all the polygons are rendered in wireframe mode after translating them backwards. If desired, the width and color of the edges of any back-facing polygon can be modified according to, say, the distance and orientation with respect to the camera (or the light source), relative importance or size of image. The line segment in the framebuffer is usually rendered with constant thickness and at the same depth value as that of the corresponding polygon edge. This creates visible silhouette edges with constant thickness. This method is very easy to implement and works well when the dihedral angles between adjacent front facing and back-facing polygons are not large. Boundary edges (edges that belong to only one polygon) or any pre-determined edges (such as sharp edges) can be specified separately and rendered along with the edges of back-facing polygons.

As the line width increases, however, one begins to see gaps between silhouette edges made up of neighboring polygons. Because two different types of primitives are involved, polygons and lines, this method also has restrictions when implemented with traditional polygon rendering pipeline.

3.2. Translated Back-facing Polygons

To increase the area of intersection, we can render front-facing polygons as usual and then render (filled) back-facing polygons pulled slightly forward towards the camera with the depth function set to 'Less than or Equal'. A larger part of the back-facing polygons appear in front of the previously occluding front-facing polygons and this overcomes the problem of numerical precision of the depth buffer. This can be done in the following ways when back-facing polygons are rendered :

- translate back-facing polygons towards the camera by a fixed amount, *t*.
- translate back-facing polygons towards the camera by $k*z$, where z is the average distance from polygon to the camera and k is a scaling constant. This is a z-scaled translation towards the camera and takes care of non-uniform resolution of depth buffer. We can achieve it by any of the two methods

1. We can scale down (typically by 0.95 to 0.99) the model with respect to the camera. Back-facing polygons closer to camera will be translated a smaller distance and polygons further away will be translated a greater distance.
2. We can change the depth-range of the view frustum by moving near or far planes i.e. either move the near z plane further back or move the far z plane closer.

- use an API call such as *glPolygonOffset()* . This allows not just z-dependent scaling but also takes into account the orientation of the polygon with respect to camera. In our case for example, polygons perpendicular to the camera need to be translated forward less than polygons that are viewed almost edge on so that their screen space contributions remain the same.

If the scaling factor used in translation is sufficiently large, this method creates smooth and continuous silhouette edges. Depending on the dihedral angle between adjacent front facing and back-facing polygons, artistic line drawings with varying line widths are rendered. This looks fine if dihedral angles between adjacent faces are similar e.g. in highly tessellated smooth curved objects. But the width of rendered silhouette edges can become overly large at sharp edges.

It is easy to see why translation of back-facing polygons will not create uniform line width silhouettes. The width of the resulting silhouette is dependent on the orientation of the back-facing polygon and also the orientation of the corresponding occluding front facing polygon.

If V is the view direction, and for silhouette edge E, N_F is the normal of the front facing polygon F and N_B is the normal for back-facing polygon B, then the part of B, that will be 'pushed' in front of the adjacent front facing polygon, F, is dependent on $V \bullet N_B$ and $V \bullet N_F$, as shown in Fig 2.

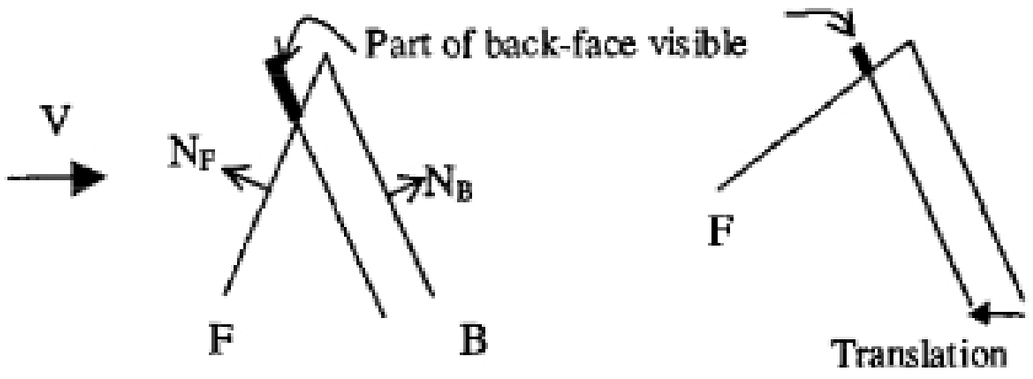

Figure 2. Projection width of visible part of back-face depends on normal of adjacent front facing polygon and back facing polygons

Depending on taste, the non-uniform width can be considered a feature or a problem. The non-uniform width may provide a pleasing hand drawn appearance, and thus the simple translation approach may be suitable for many applications. On the other hand, if uniform line width is desired, then adjacency information is needed to use the translation methods. This is a requirement we would like to avoid.

3.3. View-dependent Modification of Back-facing Polygons

Assuming polygons are convex, constant width silhouette edges can be drawn using 'fat' back-facing polygons so that the projection of extra area in the image plane is of constant width. The back-facing polygon is fattened by pushing outwards each edge by a distance proportional to $z/(V \bullet N_B)$ normal to the edge, where, z is the distance of the midpoint of the edge from the camera.

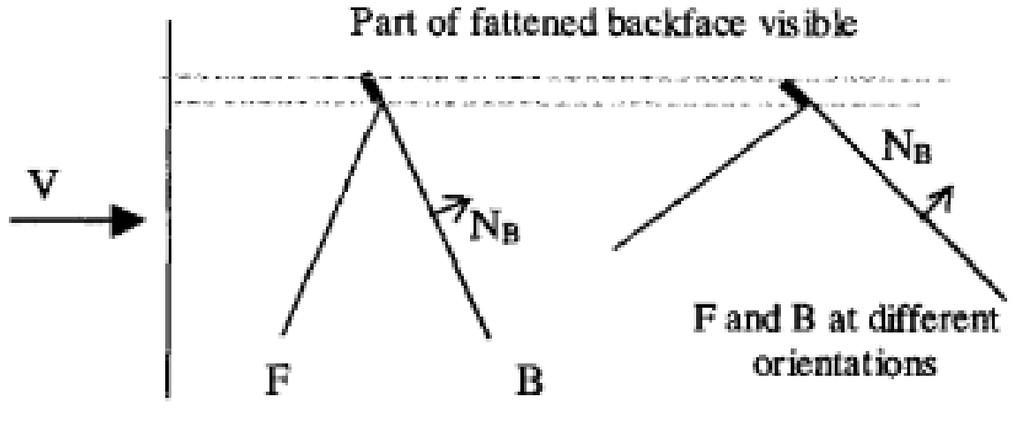

Figure 3. Fattening is dependent only on the orientation of back facing polygon

However, the required fattening is also dependent on the orientation of the edges of the back-facing polygon (i.e., fattening is different in different directions for the same polygon). If E is the edge vector so that $cos(\alpha) = V \bullet E$ for a back-facing polygon with normal N_B and distance to the camera z, then the required fattening for the edge E is proportional to $z*sin(\alpha)/(V \bullet N_B)$ in the direction $E \times N_B$. (In general, z and V can be approximated and calculated only once for the centroid of the polygon.)

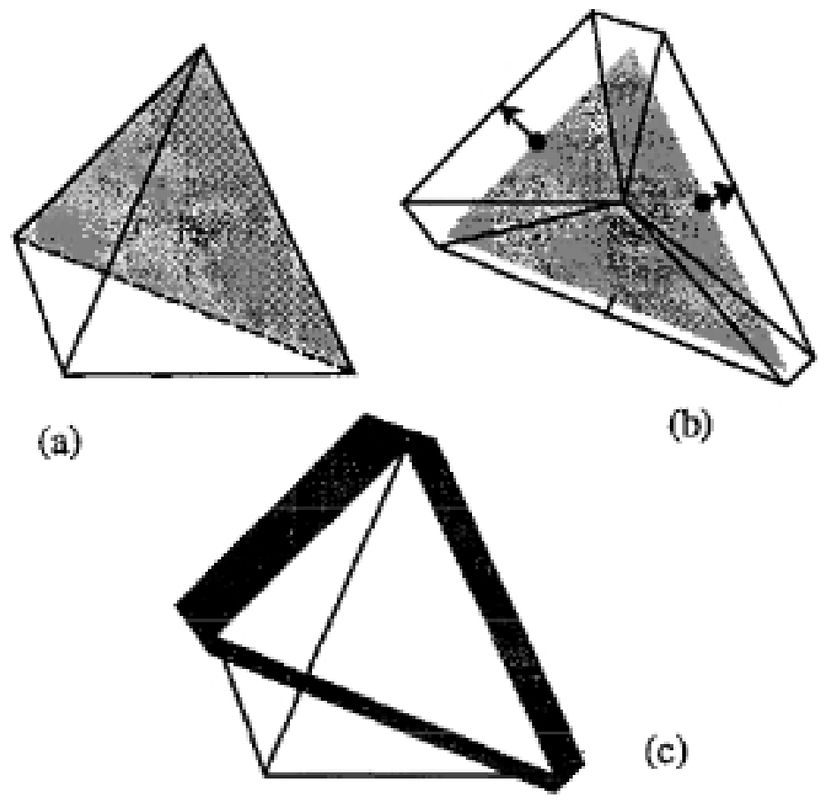

Figure 4. The backfacing polygon in (a) is fattened by pushing the edges outwards and creating a triangle fan (b). When rendered in black, they appear as silhouettes (c).

After fattening, an n-sided polygon has $2n$ vertices connected with the n original edges and small gaps between the split vertices. Completing the fattened polygon involves connecting the shifted vertices and triangulating. The triangulation is achieved by connecting all the new vertices to the midpoint of the polygon. Thus a single polygon is subdivided into $2n$ triangles in the form of a triangle fan (Figure 4).