

Name (print): KEY

Section _____ Table _____

Honor Code: I have neither given nor received unauthorized aid on this test

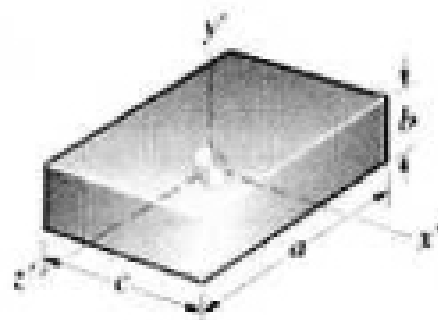
Signature: _____

ME 201 Test #3

Fall 2009

NOTES:

- *Sign and provide identifying info on every sheet.*
- *Use proper vector notation in all cases where vectors are used.*
- *In cases involving Newton's Laws, you are **REQUIRED** to draw complete and correct FBDs and when the problem is dynamics, you must also draw complete and correct KDs. Then use these to develop your governing equations.*
- *If you use your calculator to perform any calculus that might involve trig or similar functions, set your calculator to the radian mode first.*
- *In all cases, remember to show results with magnitude, direction, units and put your answer in a box.*



Rectangular prism

$$\text{Volume} = abc$$

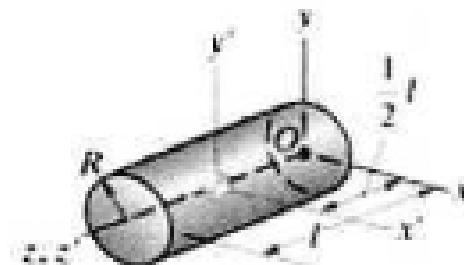
$$I_{x' \text{ axis}} = \frac{1}{12} m(a^2 + b^2), \quad I_{y' \text{ axis}} = \frac{1}{12} m(a^2 + c^2),$$

$$I_{z' \text{ axis}} = \frac{1}{12} m(b^2 + c^2),$$

$$\text{Volume} = \pi R^2 l$$

$$I_{x \text{ axis}} = I_{y \text{ axis}} = m \left(\frac{1}{3} l^2 + \frac{1}{4} R^2 \right), \quad I_{z \text{ axis}} = \frac{1}{2} m R^2,$$

$$I_{x' \text{ axis}} = I_{y' \text{ axis}} = m \left(\frac{1}{12} l^2 + \frac{1}{4} R^2 \right), \quad I_{z' \text{ axis}} = \frac{1}{2} m R^2,$$



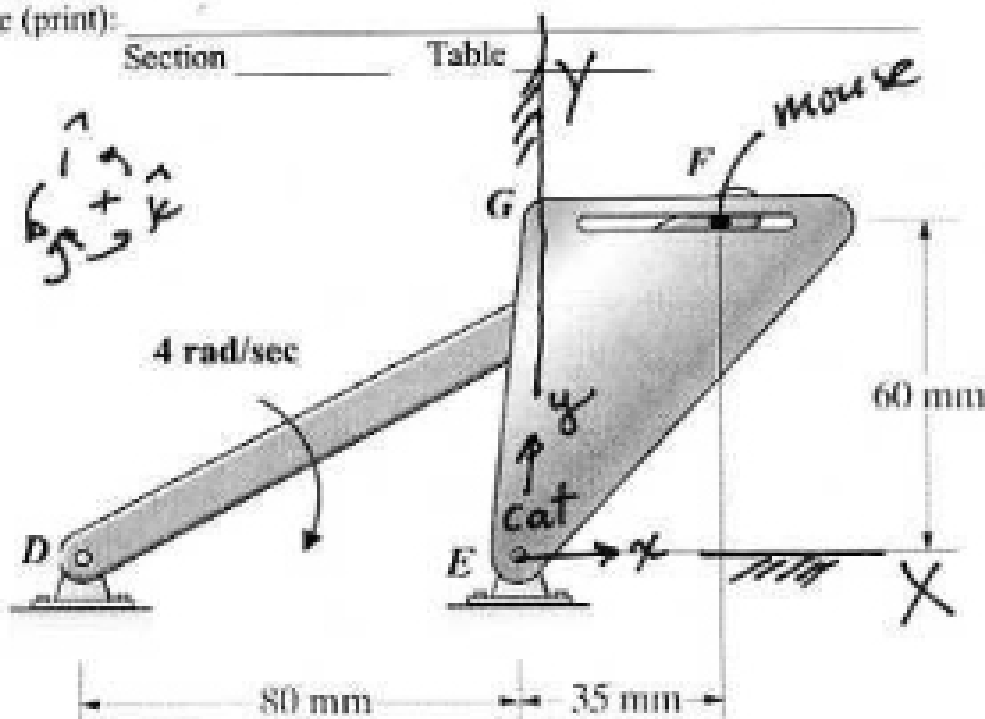
Circular cylinder

For a uniform slender bar with radius very small compared to length, these simplify to the familiar values about CG and end, respectively: $I_{CG} = m l^2/12$ and $I_{end-x} = m l^2/3$, and z-axis values go to zero.

For a uniform circular disk with thickness very small compared to radius, these simplify to the familiar values about CG: $I_{CG} = m R^2/4$ and $I_{CG} = m R^2/2$.

1. (33 pts) Bar DF has a constant angular velocity of 4 rad/sec in the clockwise direction. The small pin at F is attached to bar DF and slides in the slot in body EG . At the instant shown, the slot in body EG is horizontal. At this instant,

- find the angular velocity of body EG , and
- find the angular acceleration of body EG .



Using $D-F$:

$$\underline{\text{VEL}}: \vec{v}_F = \vec{v}_D + \vec{\omega}_{DF} \times \vec{r}_{F/D}$$

$$\underline{\text{ACCEL}}: \vec{a}_F = \vec{a}_D + \vec{\alpha}_{DF} \times \vec{r}_{F/D} - \omega_{DF}^2 \vec{r}_{F/D} = (-1840\hat{i} - 960\hat{j}) \text{ mm/sec}^2$$

Using F as mouse moving on EG . Let cat be at E + align XYZ + xyz $\therefore \hat{i} = \hat{I} \quad \hat{j} = \hat{J} \quad \hat{k} = \hat{K}$

$$\underline{\text{VEL}}: \vec{v}_F = \vec{v}_E + \vec{v}_{F/E} + \vec{\omega}_{EG} \times \vec{r}_{F/E}$$

$$240\hat{i} - 460\hat{j} = \vec{0} + v_{F/E}\hat{i} + \omega_{EG}\hat{k} \times (35\hat{i} + 60\hat{j})$$

$$= (v_{F/E} - 60\omega_{EG})\hat{i} + 35\omega_{EG}\hat{j}$$

$$\left. \begin{array}{l} \hat{i}: 240 = v_{F/E} - 60\omega_{EG} \\ \hat{j}: -460 = 35\omega_{EG} \end{array} \right\} \therefore \boxed{\omega_{EG} = -13.14 = 13.14 \frac{\text{rad}}{\text{sec}}}$$

$$v_{F/E} = -548.4 \frac{\text{mm}}{\text{sec}}$$

$$\underline{\text{ACCEL}}: \vec{a}_F = \vec{a}_E + \vec{a}_{F/E} + \dot{\omega}_{EG} \times \vec{r}_{F/E} - \omega_{EG}^2 \vec{r}_{F/E} + 2\omega_{EG} \times \vec{v}_{F/E}$$

$$-1840\hat{i} - 960\hat{j} = a_{F/E}\hat{i} + \dot{\omega}_{EG}\hat{k} \times (35\hat{i} + 60\hat{j}) - (-13.14)^2 (35\hat{i} + 60\hat{j}) + 2(-13.14\hat{k}) \times (-548.4\hat{i})$$

$$\left. \begin{array}{l} \hat{i}: -1840 = a_{F/E} - 60\dot{\omega}_{EG} - 6043.1 \\ \hat{j}: -960 = 35\dot{\omega}_{EG} + 4052.4 \end{array} \right\} \therefore \boxed{\dot{\omega}_{EG} = -143.2 = 143.2 \frac{\text{rad}}{\text{sec}^2}}$$

$$a_{F/E} = -4389.6 \frac{\text{mm}}{\text{sec}^2}$$

USE WORK-ENERGY

2. (33 pts) The 4-kg uniform bar is 1.2 m long. The pins at each end slide in the stationary frictionless slots. The spring constant $k = 180$ N/m. The spring is unstretched when the bar is vertical ($\theta = 0^\circ$). The system is released from rest when $\theta = 10^\circ$. Find the angular velocity of the bar when $\theta = 20^\circ$.

$S = 1.2(1 - \cos \theta) = \text{stretch as f.u. of } \theta$

@ $\theta = 10^\circ$ $S_1 = 0.01823$ m

@ $\theta = 20^\circ$ $S_2 = 0.07237$ m

kinetics:

$T_1 + U_{1 \rightarrow 2} = T_2$: $4(9.81)(0.02707) - \frac{180}{2} (.07237^2 - .01823^2) = T_2$
 $0.62077 \text{ N}\cdot\text{m} = \frac{1}{2} m v_G^2 + \frac{1}{2} I_G \omega_2^2$

kinematics: eq 7-7 at position (2):

we observe $\bar{v}_A = -v_A \hat{j}$ $\bar{v}_B = v_B \hat{i}$ using A+B

we have $\bar{v}_A = \bar{v}_B + \bar{\omega}_2 \times \bar{r}_{A/B}$

$-v_A \hat{j} = v_B \hat{i} + \omega_2 \hat{k} \times (1.2(-\sin 20 \hat{i} + \cos 20 \hat{j}))$
 $= (v_B - 1.2 \cos 20 \omega_2) \hat{i} + (-1.2 \sin 20 \omega_2) \hat{j}$

\hat{i} : $0 = v_B - 1.2 \cos 20 \omega_2$ $v_B = 1.1276 \omega_2 \rightarrow$

\hat{j} : $-v_A = -1.2 \sin 20 \omega_2$ $v_A = 0.4104 \omega_2 \downarrow$

Now using B+G (could use A+G just as well):

$\bar{v}_G = \bar{v}_B + \bar{\omega}_2 \times \bar{r}_{G/B} = 1.1276 \omega_2 \hat{i} + \omega_2 \hat{k} \times (0.6(-\sin 20 \hat{i} + \cos 20 \hat{j}))$

$\therefore \bar{v}_G = (1.1276 \omega_2 - .6 \cos 20 \omega_2) \hat{i} - (.6 \sin 20 \omega_2) \hat{j}$

$\bar{v}_G = 0.56378 \omega_2 \hat{i} - 0.20521 \omega_2 \hat{j}$ $v_G = 0.600 \omega_2$

Substitute in kinetics:

$0.62077 = \frac{1}{2} 4 (.600 \omega_2)^2 + \frac{1}{2} (\frac{1}{12} 4 (1.2)^2) \omega_2^2$ $\omega_2 = 0.8041 \frac{\text{rad}}{\text{sec}}$

