

Stanford CS223B Computer Vision, Winter 2005

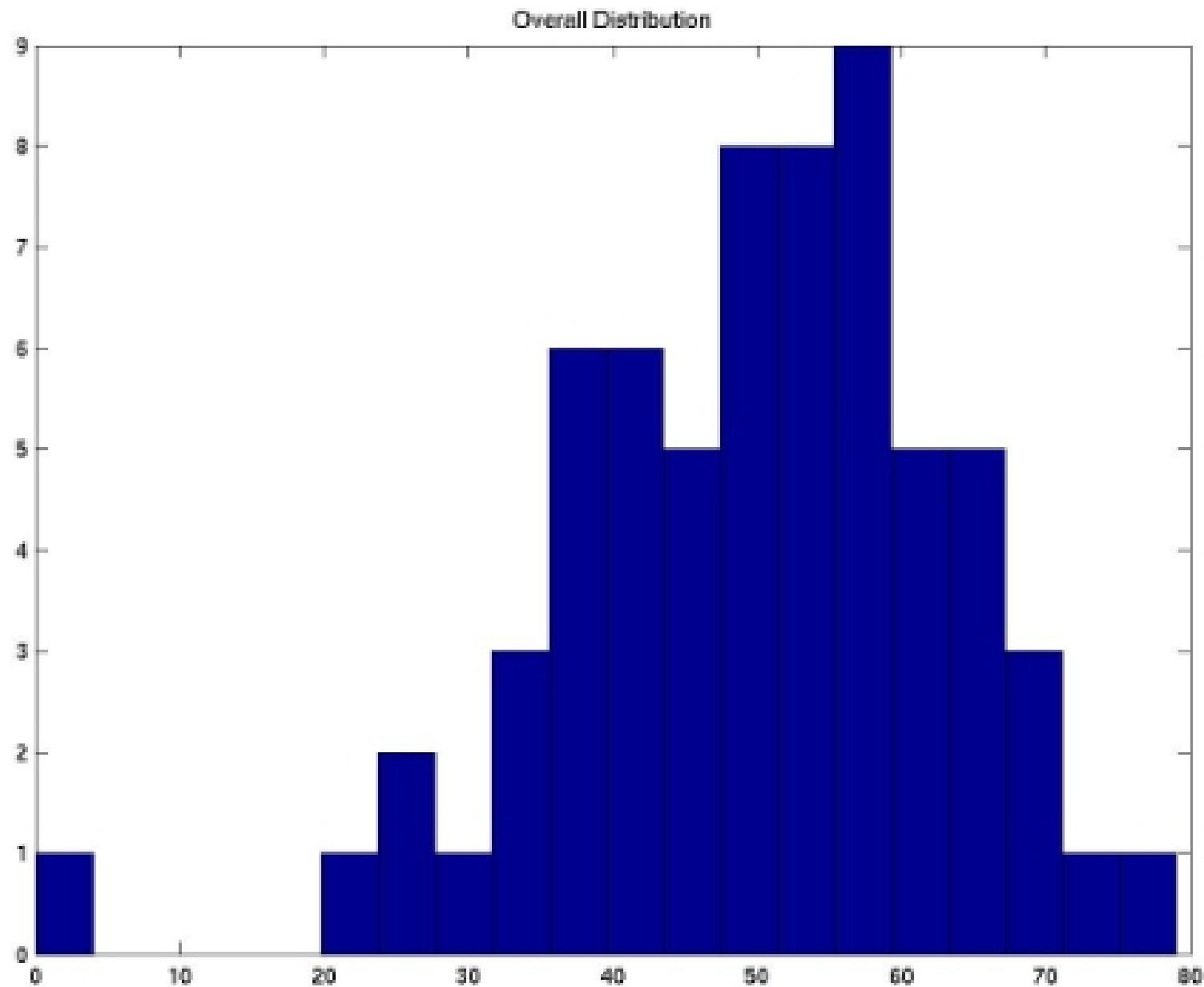
Lecture 11: **Structure From Motion 2**

Sebastian Thrun, Stanford

Rick Szeliski, Microsoft

Hendrik Dahlkamp and Dan Morris, Stanford

Overall Distribution



Question 1: Calibration

