

ME451: Control Systems

Lecture 1 Introduction

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Fall 2008

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Instructor

- **Class Instructor:** Dr. Jongeun Choi,
 - Website: <http://www.egr.msu.edu/~jchoi/>
 - Assistant Professor at ME department,
 - 2459 Engineering Building,
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- **Office Hours**
 - 2459 EB, **MW** 2:00-3:00pm, Extra hours by appointment
- **Laboratory Instructor:** Dr. C. J. Radcliffe,
 - 2445 Engineering Building
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Course information

- **Lecture:**
 - When: MWF: 11:30am-12:20pm,
 - Where: C103 McDonel Hall
- **Class website:**
<http://www.egr.msu.edu/classes/me451/jchoi/2008/>
- **Laboratory website:**
<http://www.egr.msu.edu/classes/me451/radcliff/lab>
- **Required Text:**
 - Feedback Control Systems, C. L. Phillips and R. D. Harbor, Prentice Hall, 4th edition, 2000

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Main components of the course

- **Lectures (about 40 lectures)**
- **Midterm1 (October 3rd, Friday, in class)**
- **Midterm2**
- **Final (Final exam period)**
- **Laboratory work**
- **Grading:**
 - Homework (15%), Exam 1 (15%), Exam 2 (15%), Final Exam (comprehensive) (30%), Laboratory work (25%)
 - Homework will be due in one week from the day it is assigned

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Tips to pass this course

- Come to the lectures as many times as you can.
- Print out and bring lecture slides to the lecture.
- Do “Exercises” given at the end of each lecture.
- Do homework every week.
- Read the textbook and the slides.
- Make use of instructor’s office hours.
- If you want to get a very good grade...
 - Read the textbook thoroughly.
 - Read optional references too.
 - Do more than given “Exercises”.
 - Use and be familiar with Matlab.

What is “Control”?

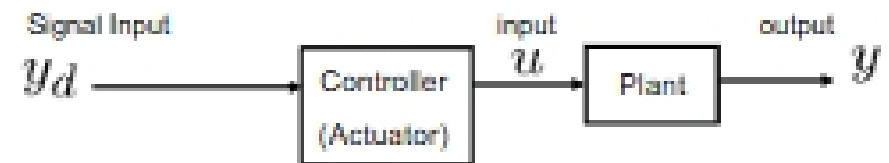
- Make some object (called **system, or plant**) behave as we desire.
- Imagine “control” around you!
 - Room temperature control
 - Car/bicycle driving
 - Voice volume control
 - “Control” (move) the position of the pointer
 - Cruise control or speed control
 - Process control
 - etc.

What is “Control Systems”?

- Why do we need control systems?
 - Convenient (room temperature control, laundry machine)
 - Dangerous (hot/cold places, space, bomb removal)
 - Impossible for human (nanometer scale precision positioning, work inside the small space that human cannot enter)
 - They exist in nature. (human body temperature control)
 - Lower cost, high efficiency (factory automation), etc.
- Many examples of control systems around us

Open-Loop Control

- Open-loop Control System
 - Toaster, microwave oven, shooting a basketball



- Calibration is the key!
- Can be sensitive to disturbances

Example: Toaster

- A toaster toasts bread, by setting timer.



- **Objective:** make bread **golden browned** and crisp.
- A toaster does **not measure** the color of bread during the toasting process.
- For a fixed setting, in winter, the toast can be white and in summer, the toast can be black (Calibration!)
- A toaster would be more expensive with **sensors** to measure the color and **actuators** to adjust the timer based on the measured color.

Example: Laundry machine

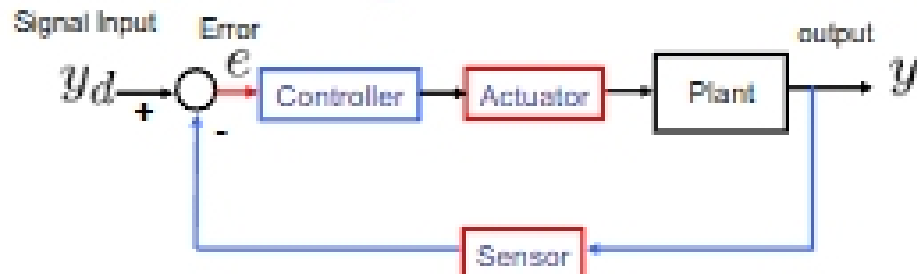
- A laundry machine washes clothes, by setting a program.



- A laundry machine does **not measure** how clean the clothes become.
- Control without measuring devices (sensors) are called **open-loop control**.

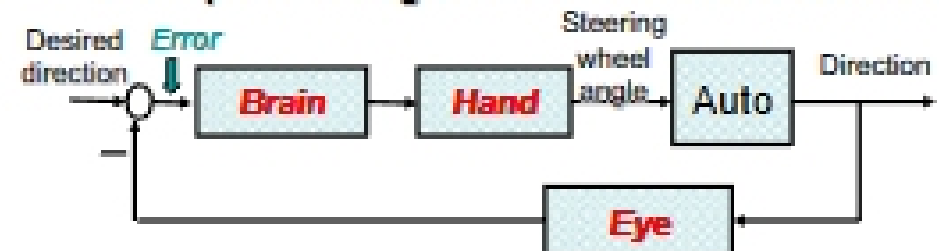
Closed-Loop (Feedback) Control

- Compare actual behavior with desired behavior
- Make corrections based on the error
- The **sensor** and the **actuator** are key elements of a feedback loop
- Design **control algorithm**



Ex: Automobile direction control

- Attempts to change the direction of the automobile.



- Manual closed-loop (**feedback**) control.
- Although the controlled system is "Automobile", the **input** and the **output** of the system can be different, depending on **control objectives**!